

# Vari-Vert 40-6 Meters

## A Flagpole'ish Antenna

Excerpt from the TVARC presentation of February 2017

by

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## An “*Electrically*” Variable Vertical

The design, construction and performance of an inexpensive “Low Observable” antenna that provides 40-6 Meter capability.

- The antenna ‘looks like’ and performs like a Flagpole.
- 20’ Flagpoles are allowed in Florida by State Statute [720.304](#) (2b).
- Commercial antennas with controllable length elements are expensive and generally require maintenance or repair ***by the manufacturer.***
- The following slides deal with an electrically similar homebrew antenna that is simple to build and easy to maintain.

# Flagpole Type Verticals

20' Flagpole, Non-Resonant (in ham bands)

- Requires a Remote Tuner at the antenna, OK
- Tuner In Operator Location, Not so good....

$\frac{1}{4} \lambda$  Resonant Vertical, so.... No Tuner

(aka; Marconi antenna)

Thinking.... SteppIR Vertical? You are close!

# Trade-Off's

## Flagpole Radiator

- Remote Tuner **Required**
  - 100 watt class or big \$\$\$
  - Tuner is somewhat delicate
  - Tuner loss, moderate
  - Cost ~\$350
    - Aluminum Flagpole
    - Tuner
    - Bias T

## $\frac{1}{4} \lambda$ Resonant Radiator

- No Tuner
  - Legal Limit, **No Tuner Loss**
  - Simple Mechanics
  - No critical dimensions
  - Cost~\$350
- Carbon Fiber Pole
  - Homebrew Mechanics
  - Enclosures, Micro Processor/Display,
  - Bias T

Not a clear winner..... BUT

***If any repair is needed you can do it yourself*** after all you built it.

A sense of accomplishment is worth something! Great talking point

# The Vari-Vert

## Parameters:

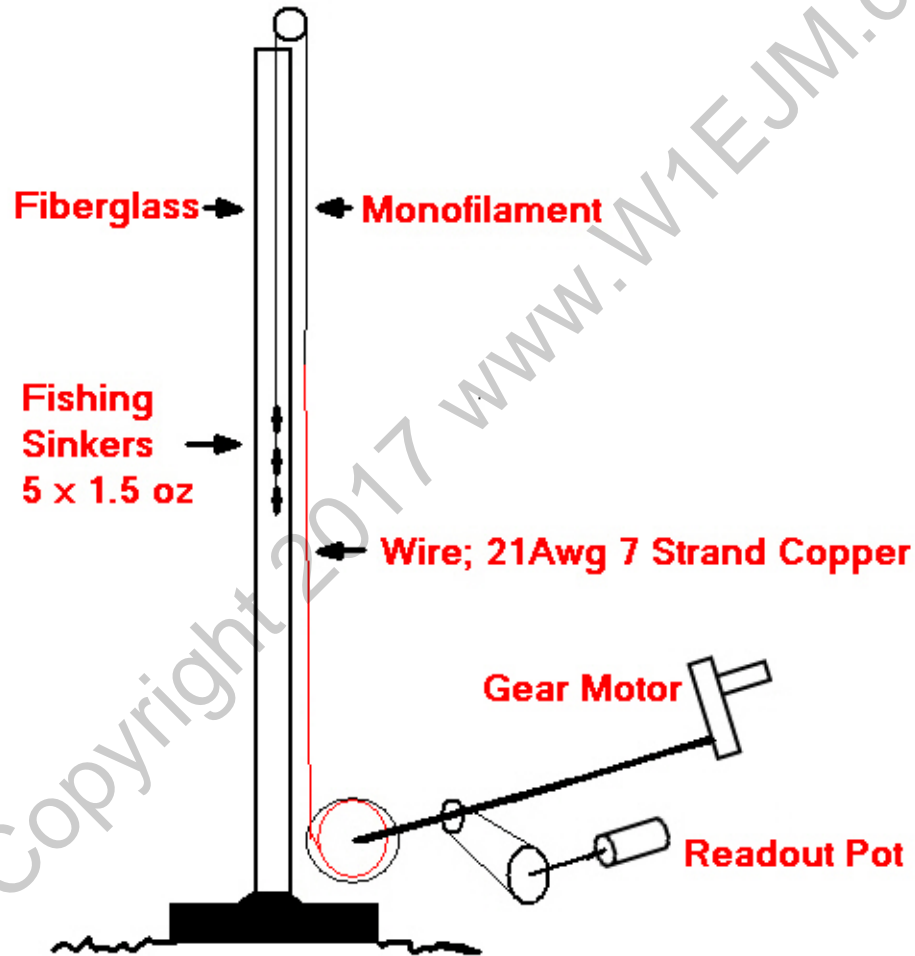
- True  $\frac{1}{4} \lambda$  Antenna
- Low Angle for DX op's
- 20 - 6 Meters - - **No Tuner needed**
- 40-30 Meters uses 2 relays and a tapped L, fixed C
- Digital Control / Readout Unit
- Build it all for ~\$350

Uses inexpensive, readily available component parts

Tools; a Dremel Rotary, a Soldering Iron and household tools

# Vari-Vert Layout

## Prototype Configuration



# “Fiberglass” Flagpole Material Properties

Carbon Fiber, non-conductive, ideal antenna support

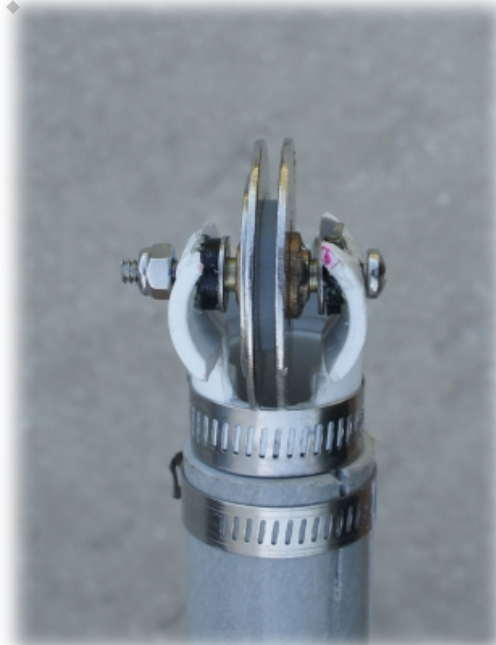
Carbon Fiber and Aluminum .... similar strength

Deflection for 20', 2"dia, 0.125 wall, 1# Force

Deflection calculator for round tube beams	
Input	Output
Length (inches) <input type="text" value="240"/>	<b>Aluminum 1.42"</b> Deflection (inches) <input type="text" value="1.417793021798"/> Bending Stress (psi) <input type="text" value="738.4338655200"/> Energy (joules) <input type="text" value="0.080093711729"/>
Diameter (inches) <input type="text" value="2"/>	
Wall thickness (inches) <input type="text" value=".125"/>	
Force (pounds) <input type="text" value="1"/>	
Material <input type="text" value="Aluminum"/>	
Deflection calculator for round tube beams	
Input	Output
Length (inches) <input type="text" value="240"/>	<b>Carbon Fiber 1.4"</b> Deflection (inches) <input type="text" value="1.396840415564"/> Bending Stress (psi) <input type="text" value="738.4338655200"/> Energy (joules) <input type="text" value="0.078910060816"/>
Diameter (inches) <input type="text" value="2"/>	
Wall thickness (inches) <input type="text" value=".125"/>	
Force (pounds) <input type="text" value="1"/>	
Material <input type="text" value="Std. Carbon Fiber Fabric"/>	

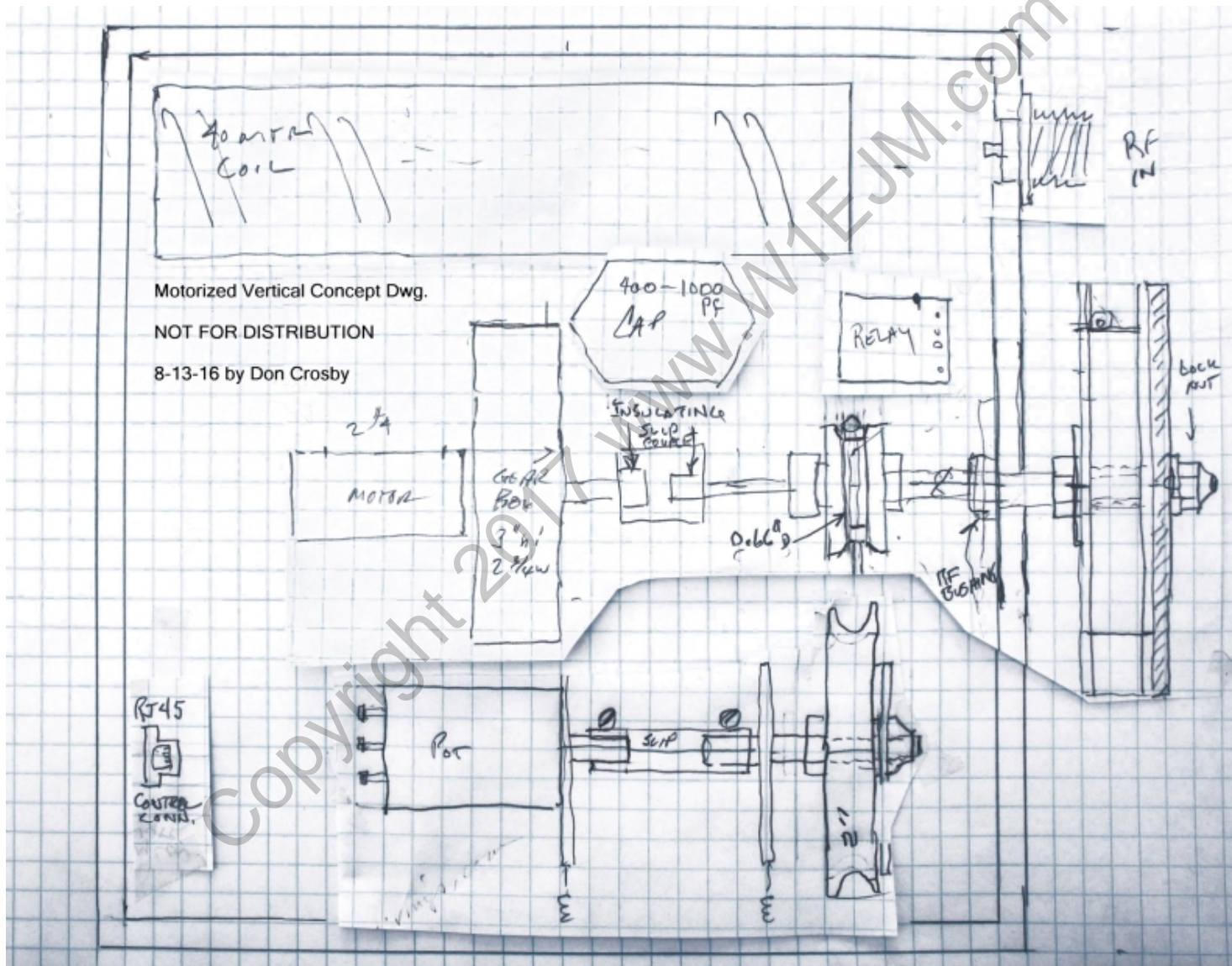
# Mast Components

- Fiberglass Pipe 8' by 1.5", 1.75", 2" dia.
- Homebrew Low Friction Pulley
- Hose Clamps between pipe sections



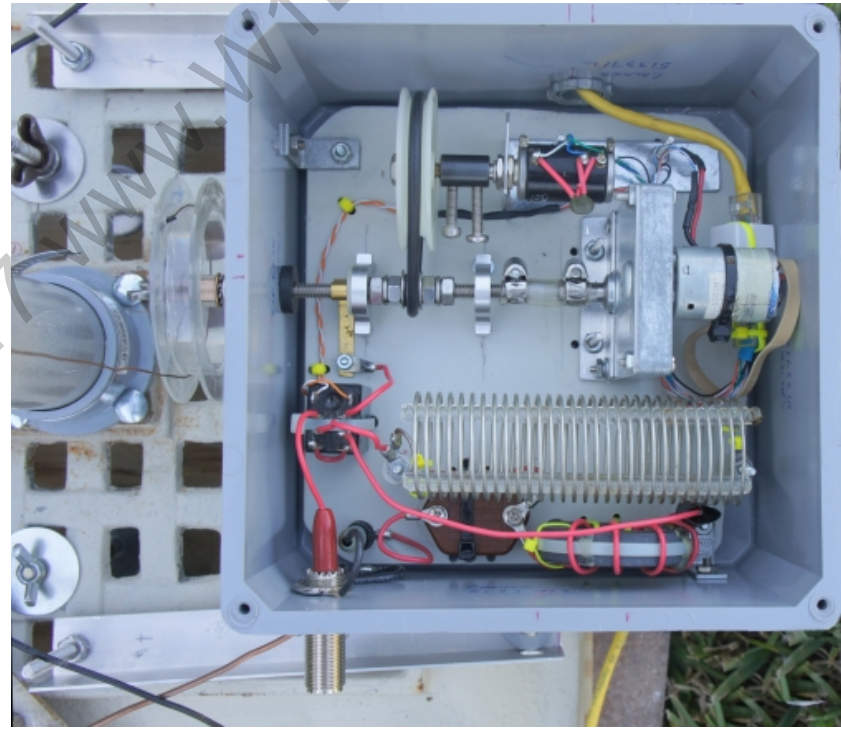


# Vari-Vert Mechanism Layout



# Vari-Vert “All-Up”

- Radiating wire length is set for  $\frac{1}{4} \lambda$



# Vari-Vert Component Trade-Off's

## Motor Options

- Brush Type DC,
- Brushless DC,
- Stepper,
- AC

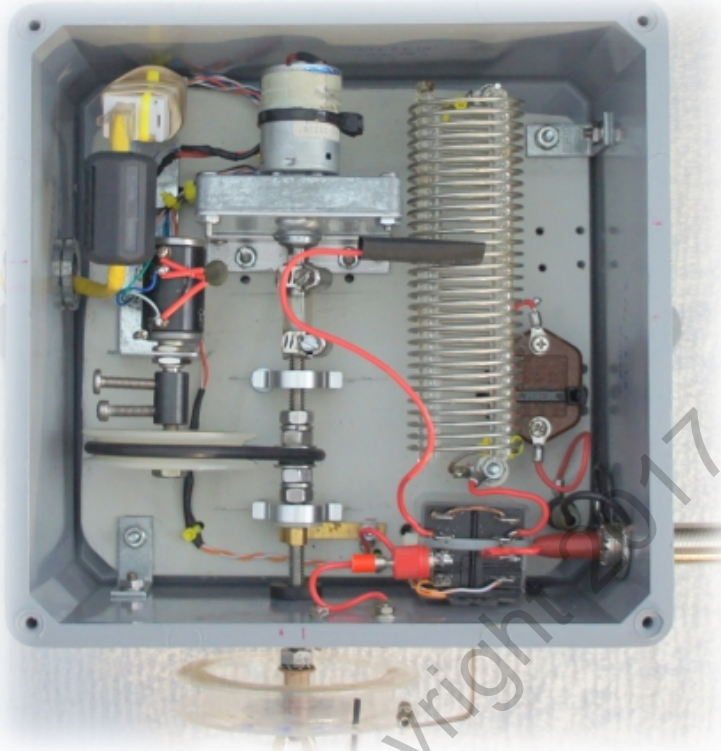
## Sensor Options

- Multi-Turn Potentiometer
- Incremental Encoder
- Absolute Encoder \$\$\$
- Mechanical Counter

I just used things on hand.

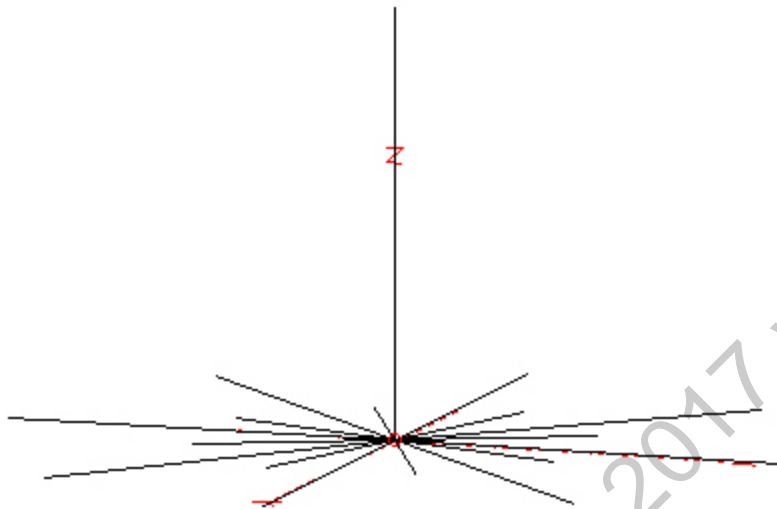
- Brush Type DC Motor
- Multi-Turn Potentiometer

# Remote Motor Box



Antenna wire “pays” off the spool and makes additional RF contact with the brass pulley and copper guide.

# Model Layout



Height is Variable

Radials 8-10' & 8-20' @

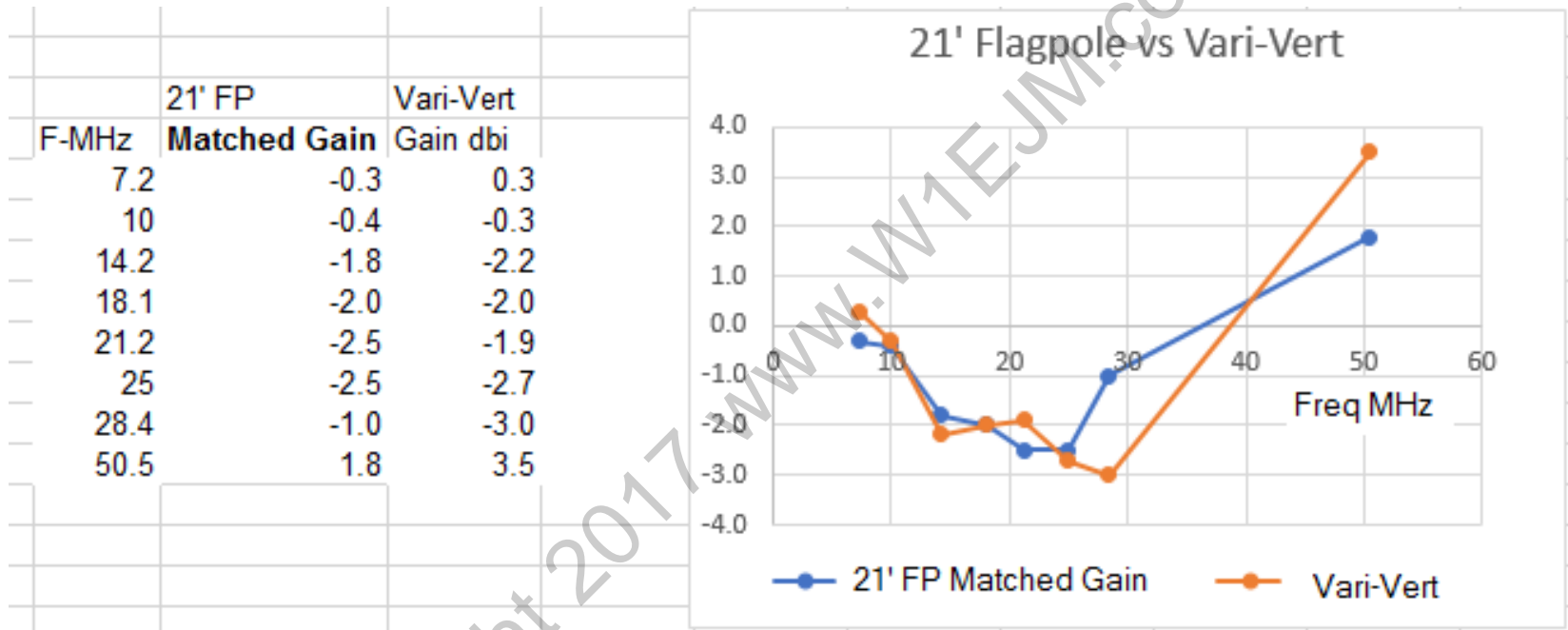
1" above Ground *for Model* \*

Average Soil  $C=5\text{ms}$ ,  $E_r=13$

Nec2 Modeling Engine

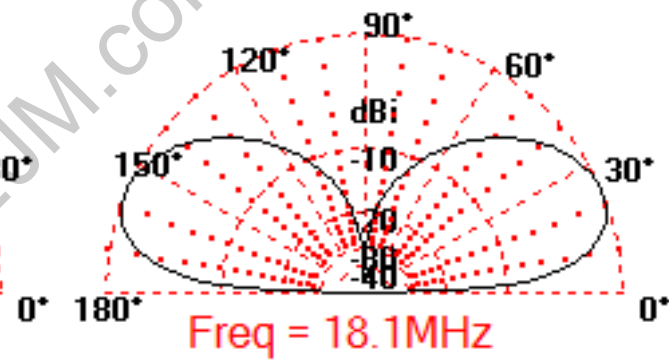
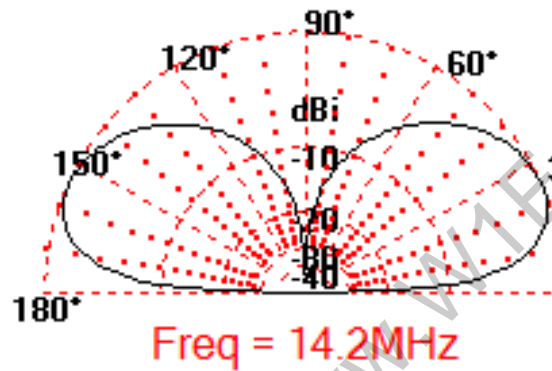
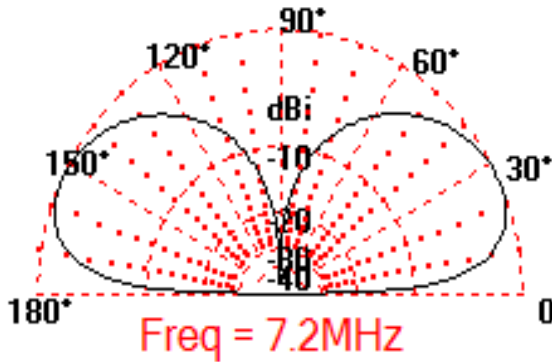
- \* The NEC-2 Modeling Engine does not permit wires below ground, but comparisons by L.B. Cebik W4RNL (SK) indicate above ground provides good correspondence

# NEC2 Modeling Predictions

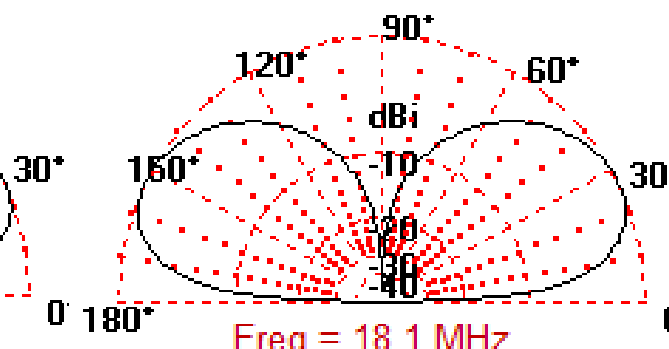
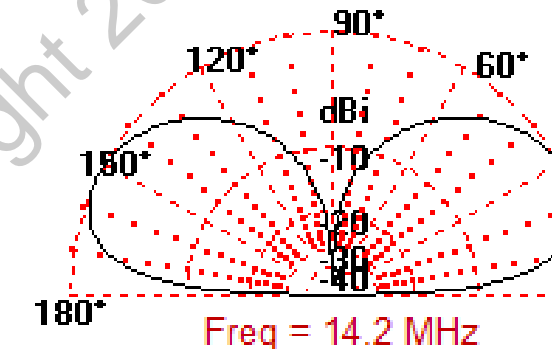
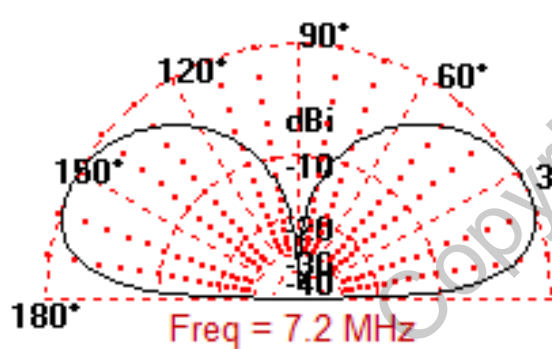


- 21' Flagpole with Tuner to Match at the FP Base
- Vari-Vert Radiator Length set to  $\frac{1}{4}\lambda$  by remote
- **Note:** Vari-Vert acts as  $\frac{3}{4}\lambda$  at 50.5 MHz

## 7.2, 14.2, and 18.1Mhz Elevation Plots Shapes



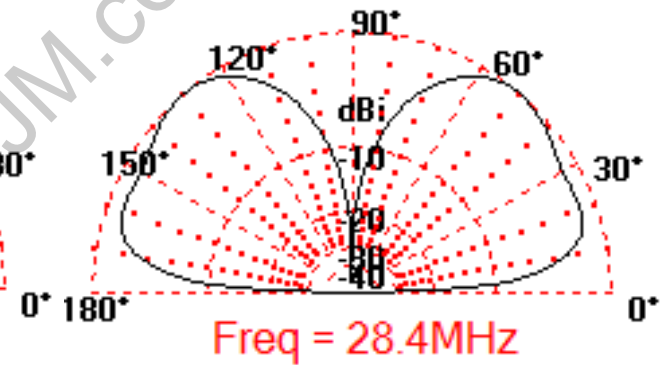
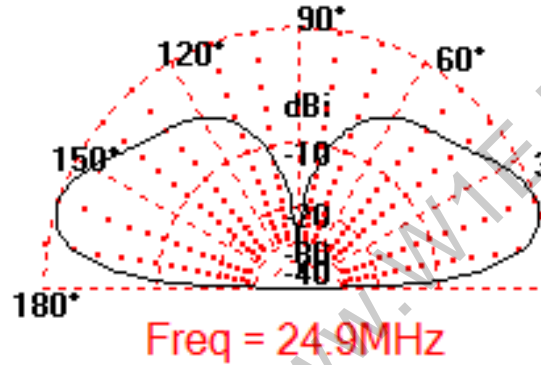
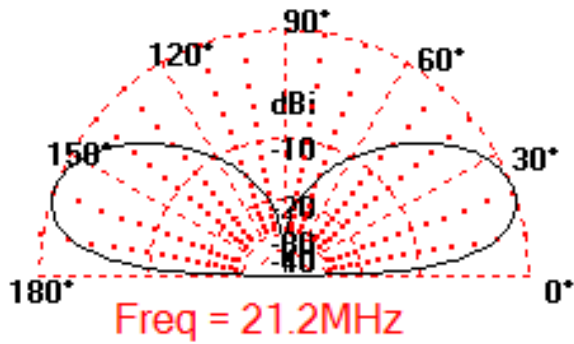
21' Flagpole



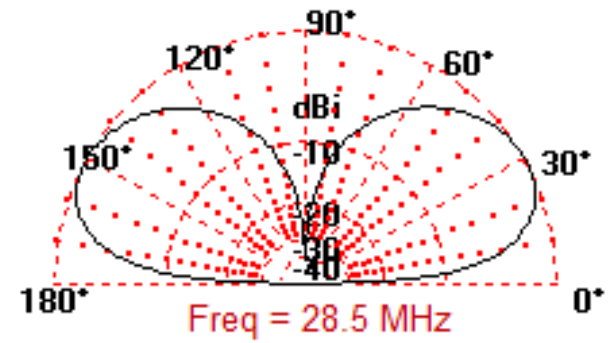
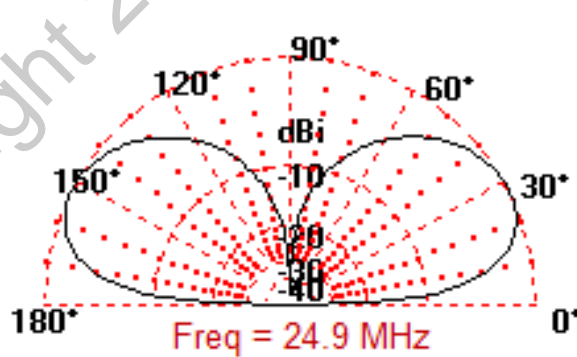
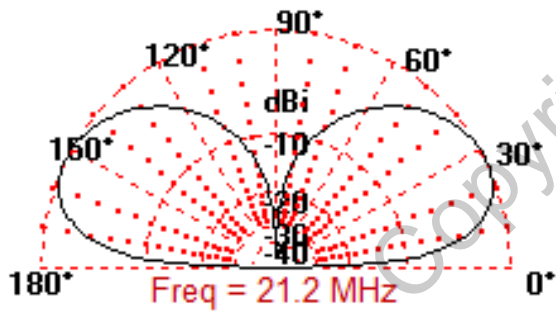
Outer Ring -0.28 dBi  
C-L Lo Pass L-Net,  
682.71 pF, 8.17 uH

Vari-Length Vertical  $\frac{1}{4} \lambda$

# 21.2, 24.9, and 28.5Mhz Elevation Plots Shapes



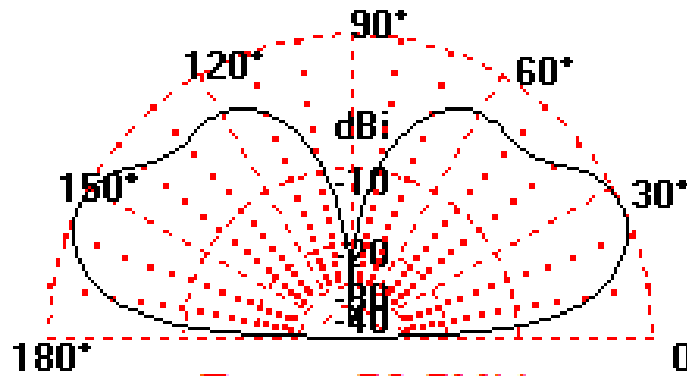
21' Flagpole



Vari-Length Vertical

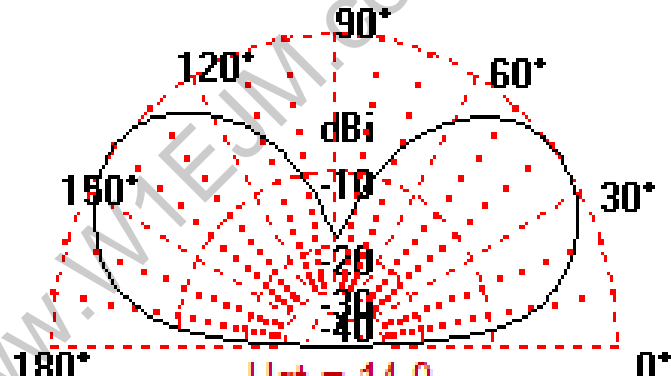


# 50.5 MHz



Freq = 50.5MHz  
Outer Ring 1.8 dBi

21' Flagpole



Hgt = 14.9  
Outer Ring 3.39 dBi

14.7' Vari-L  $\frac{3}{4} \lambda$

6 Meters the Vari-Vert works as a  $\frac{3}{4} \lambda$  vertical

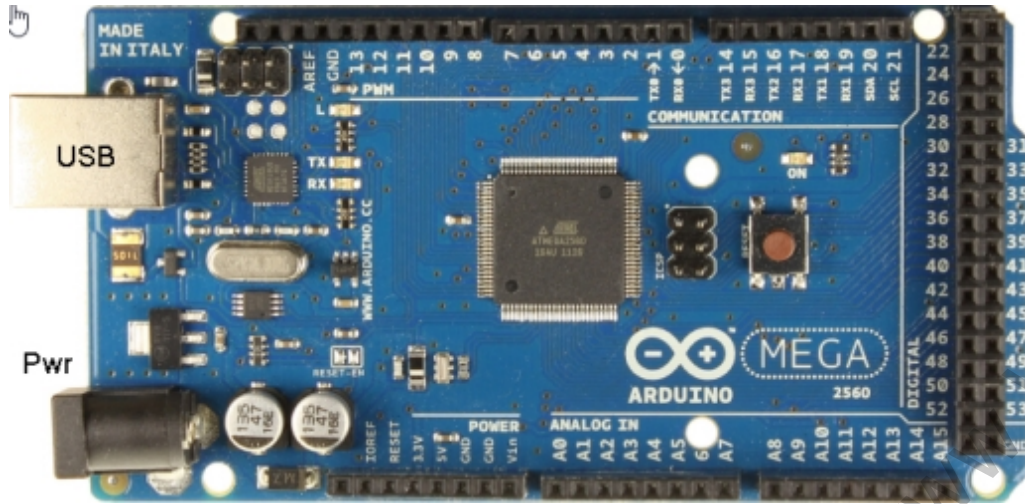
Provides ~1.6db Gain overall advantage

# Desktop Controller

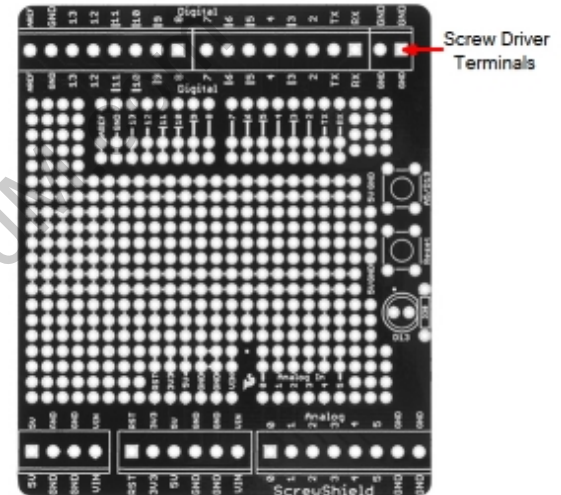
## Requirements:

- Digital display of Frequency and Length
- Smooth motor speed ramping
- Expandable functions and inexpensive
- Future features.....
  - Pushbutton command to calibrate the radiator length \*
  - Stall sensor motor shutdown \*

# Controller Components



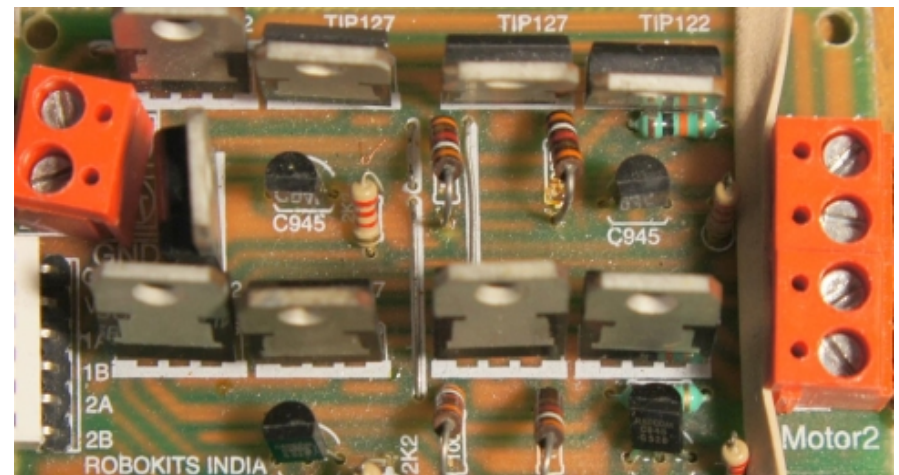
Arduino Mega 2560 \$12



Breakout Board \$15

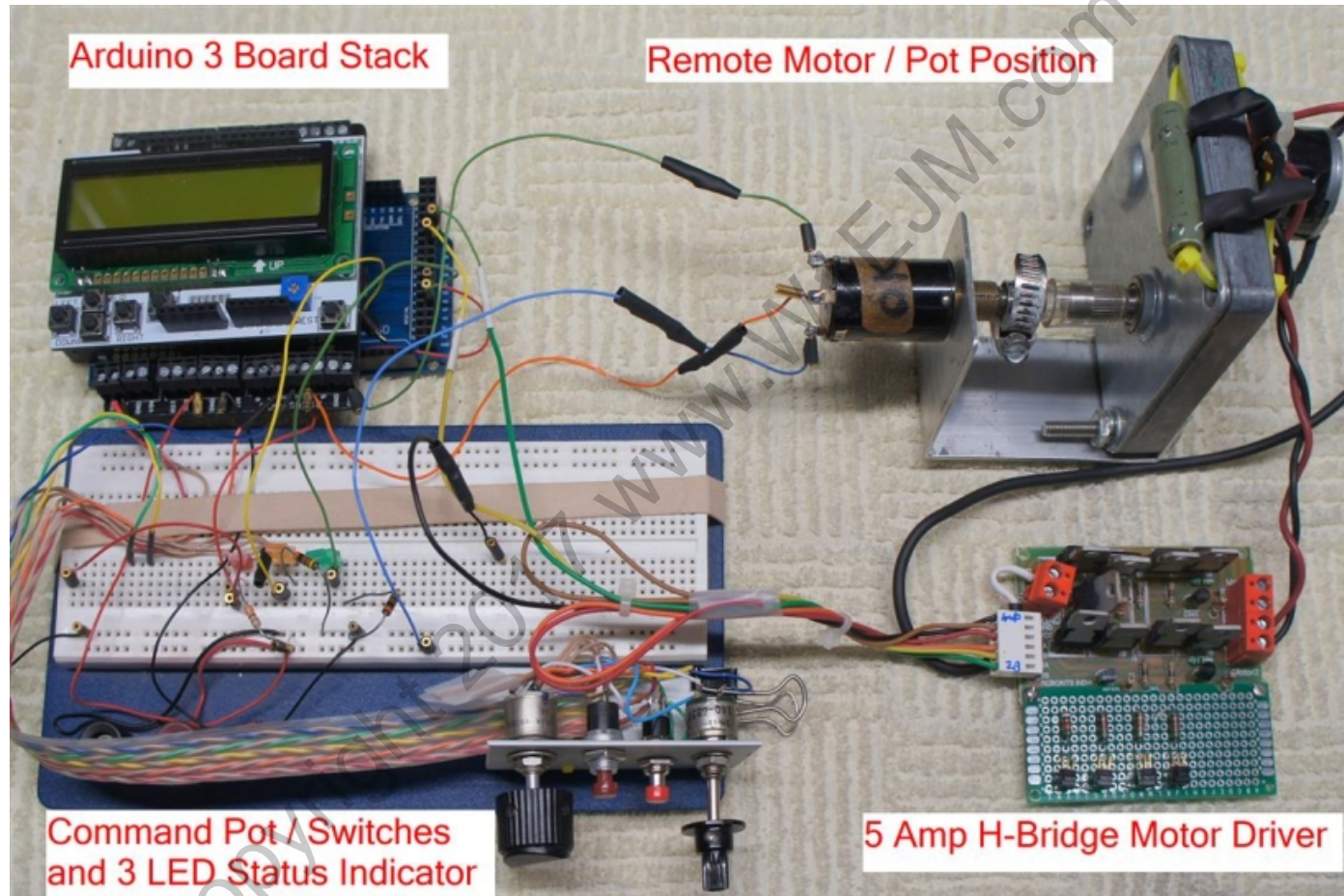


2x16 Backlit LCD \$13



Dual H Bridge Motor Driver \$5

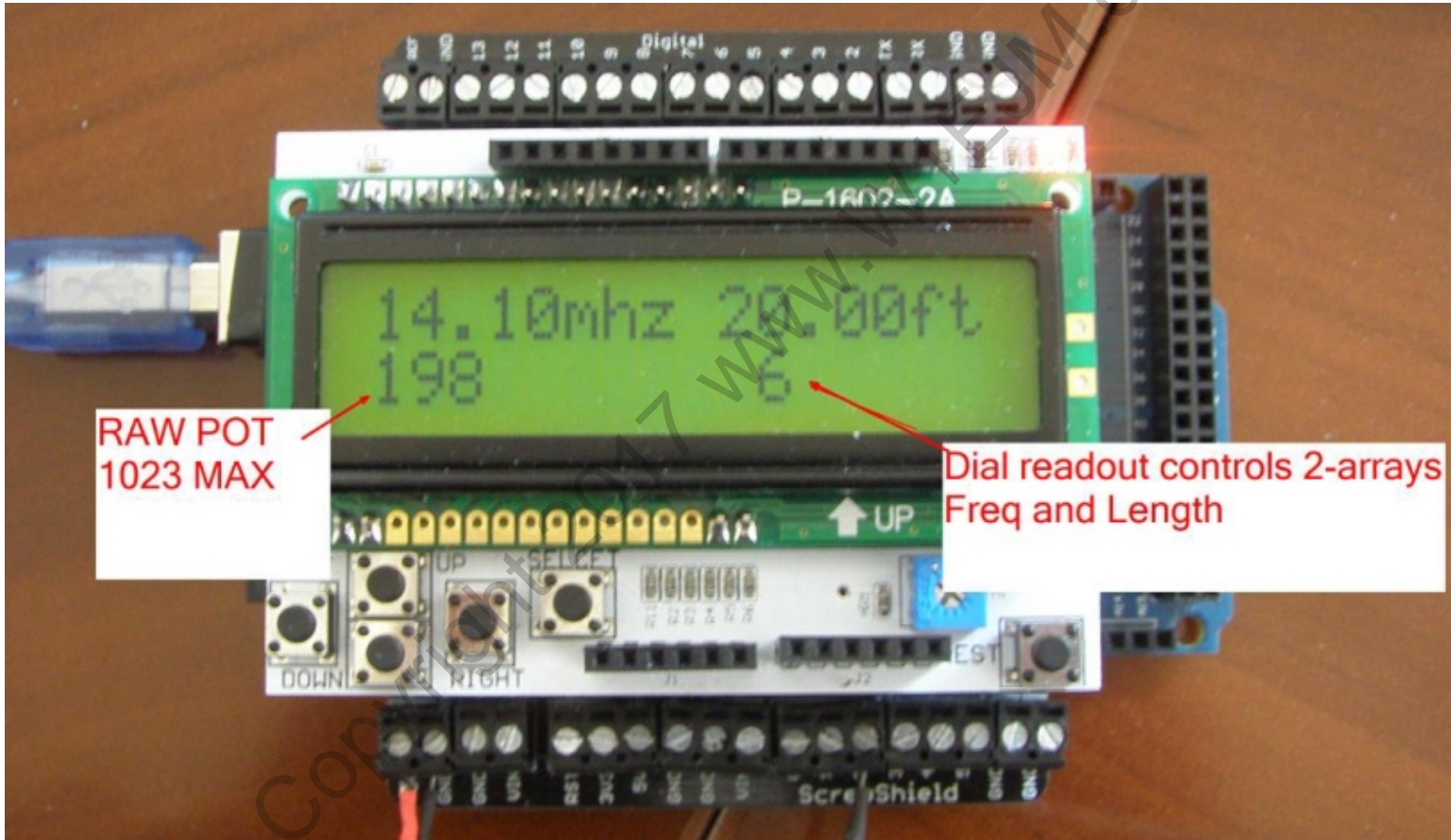
# Controller Breadboard



Arduino Development Program (Free)

Connectivity by USB to the 3 board stack

# Display Readout



# “The Programmer IDE... PC or MAC”

IDE means.. Integrated Development Environment

## – Features

- “Sketch” entry for typing in your program code
- Details any errors it uncovers in the code
- Compiles and loads the code to the target computer board
- Calculates memory usage
- Provides Serial Monitor for debugging
- Powers up the hardware through the USB

## – Arduino IDE is a FREE download

- Lots of shared software “sketches” on the web
- Good ‘forum’ support for beginners
- Lots of easy projects to get your feet wet

# Field Experience

- Operated at a local hams QTH during Nov – Dec 2016
- Good contacts and on-the-air reports operating CW at 3-5 watts
- Experienced mechanical hang-ups due to the jerky start / stop motion

## As Demo'ed at the TVARC Meeting

- Microprocessor Smart Controller was designed during the field evaluation period.
- Microprocessor code was written debugged and readied for testing
- The micro processor provided smooth start/run/stop and resolved the hang-ups

Interested in more info about this antenna?

Don, W1EJM

- QRZ.com
- Phone book
- 443.150MHz

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